

INDIAN INSTITUTE OF TECHNOLOGY KHARAGPUR
Department of Electrical Engineering
Mid-Sem Semester, September 25, 2012

Time: 2 Hours

EE 41013: Digital Signal Processing

Full Marks: 120

Answer all questions. Make suitable assumptions wherever necessary

Q.1 A sequence has the discrete-time Fourier transform $X(e^{j\omega}) = \frac{1-a^2}{(1-ae^{-j\omega})(1-ae^{j\omega})}$ $|a| < 1$ [15]

(a) Find the sequence $x[n]$. (b) Calculate $\frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\omega}) \cos(\omega) d\omega$.

Q.2 An ideal low-pass filter with zero delay has impulse response $h_{lp}[n]$ and frequency response

$$H_{lp}(e^{j\omega}) = \begin{cases} 1, & |\omega| < 0.2\pi, \\ 0, & 0.2\pi \leq |\omega| \leq \pi \end{cases} \quad [15]$$

A new filter is defined by the equation $h[n] = \frac{\sin(0.1\pi n)}{\pi n} h_{lp}[n]$. Determine the equation for the frequency response $H(e^{j\omega})$, and approximately plot the nature for $|\omega| < \pi$.

Q.3 The autocorrelation sequence of a signal $x[n]$ is defined as $R_x[n] = \sum_{k=-\infty}^{\infty} x^*[k]x[n+k]$ [5+10]

(a) Show that for an appropriate choice of the signal $g[n]$, $R_x[n] = x[n] * g[n]$, and identify the proper choice for $g[n]$.

(b) Show that the Fourier transform of $R_x[n]$ is equal to $|X(e^{j\omega})|^2$.

Q.4 In Fig.Q4

(a) Prove that the overall system in the dotted box is LTI.

(b) Determine an expression for $H(e^{j\omega})$, the frequency response of the overall system in terms of $H_1(e^{j\omega})$, the frequency response of the internal LTI system.

(c) Find and approximately show the nature of $H(e^{j\omega})$ for the case when the frequency response of the

internal LTI system is $H_1(e^{j\omega}) = \begin{cases} 1, & |\omega| < \omega_c, \\ 0, & \omega_c < |\omega| \leq \pi. \end{cases}$

[15]

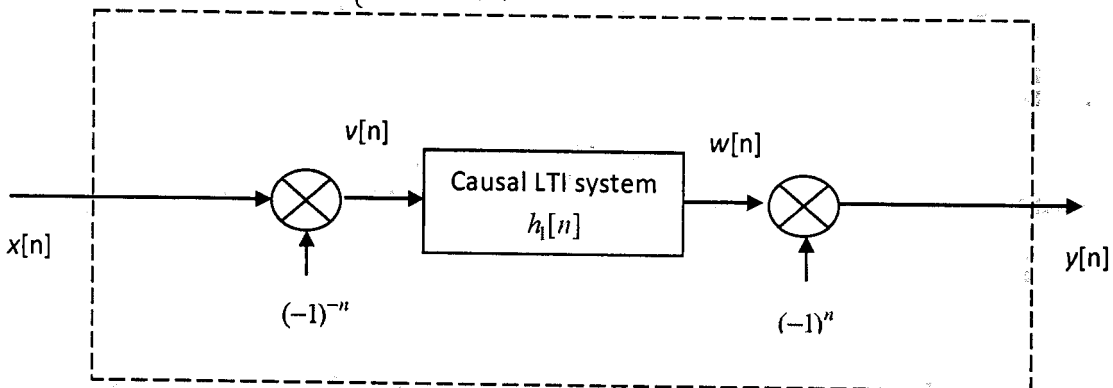


Fig.Q.4

Q.5 Determine the Z-transform of each of the following sequences including the ROC [8+7]

$$(a) \sum_{k=-\infty}^{\infty} \delta[n-4k]$$

$$(b) \frac{1}{2} [e^{j\pi n} + \cos(\frac{\pi}{2}n) + \sin(\frac{\pi}{2} + 2\pi n)]u[n]$$

Q.6 Consider an LTI system that is stable and for which $H(z)$, the z -transform of the impulse response,

is given by $H(z) = \frac{3-7z^{-1}+5z^{-2}}{1-\frac{5}{2}z^{-1}+z^{-2}}$. Find the output when the input is a unit step sequence. [15]

Q.7 Consider the system shown in the Fig.Q.7. For each of the following input signals $x[n]$, indicate whether the output $x_r[n] = x[n]$. [15]

$$(a) x[n] = \cos(\pi n / 4) \quad (b) x[n] = \left[\frac{\sin(\pi n / 8)}{\pi n} \right]^2$$

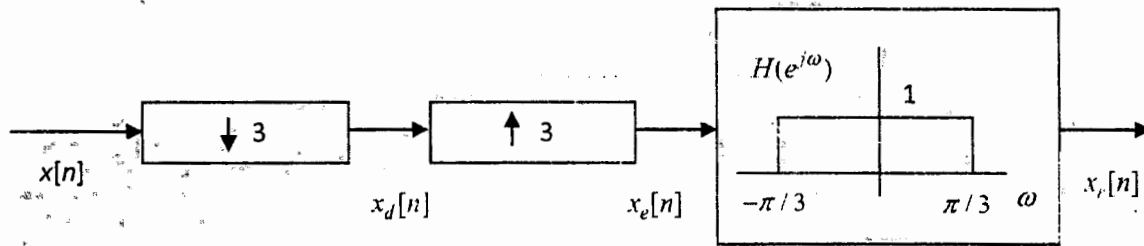


Fig.Q.7

Q.8 In the system of the Fig.Q.8, assume that $X_c(j\Omega) = 0$ for $|\Omega| > \pi / T$. Determine and approximately plot the magnitude and phase of the frequency response of the discrete-time LTI system such that the output is $y_r(t)$ is the running integral of the input, i.e. $y_r(t) = \int_{-\infty}^t x_c(\tau) d\tau$. [15]

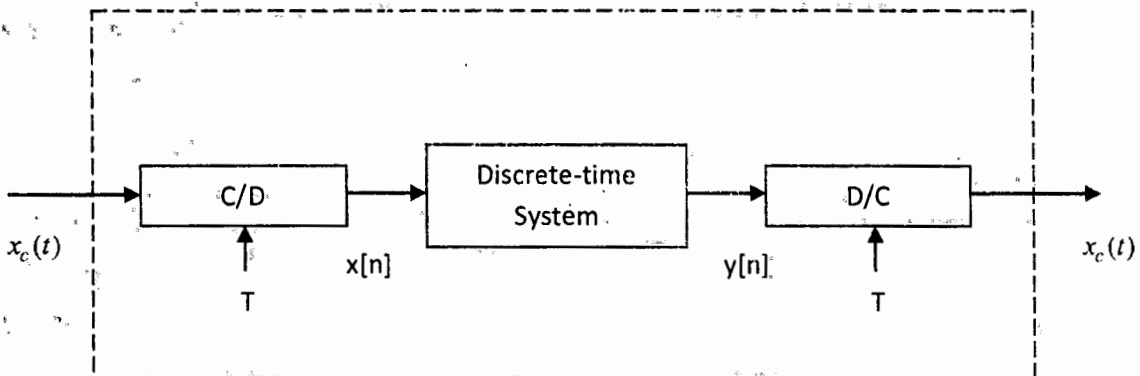


Fig.Q.8